

# A very complicated proof of the minimax theorem

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<http://carma.newcastle.edu.au/meetings/evims/>  
<http://www.carma.newcastle.edu.au/jon/minimax.pdf>

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# Contents:

It is always worthwhile revisiting ones **garden**

- 1 Abstract
- 2 Introduction
  - Classic economic minimax
  - General convex minimax
- 3 Various proof techniques
  - Four approaches
- 4 Five Prerequisite Tools
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  - Lagrange duality
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## Abstract

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Then I shall reproduce the most complex one I am aware of.

This provides a fine didactic example for many courses in convex analysis or functional analysis.

This will also allow me to discuss some lovely basic tools in convex and nonlinear analysis.

- Companion paper to appear in new journal of *Minimax Theory and its Applications* and is available at <http://www.carma.newcastle.edu.au/jon/minimax.pdf>.



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The classical von Neumann minimax theorem is:

### Theorem (Concrete von Neumann minimax theorem (1928))

Let  $A$  be a linear mapping between Euclidean spaces  $E$  and  $F$ . Let  $C \subset E$  and  $D \subset F$  be nonempty compact and convex. Then

$$d := \max_{y \in D} \min_{x \in C} \langle Ax, y \rangle = \min_{x \in C} \max_{y \in D} \langle Ax, y \rangle =: p. \quad (1)$$

In particular, this holds in the economically meaningful case where both  $C$  and  $D$  are *mixed strategies* – simplices of the form

$$\Sigma := \left\{ z : \sum_{i \in I} z_i = 1, z_i \geq 0, \forall i \in I \right\}$$

for finite sets of indices  $I$ .

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More generally we have:

### Theorem (Von Neumann-Fan minimax theorem)

Let  $X$  and  $Y$  be Banach spaces. Let  $C \subset X$  be nonempty and convex, and let  $D \subset Y$  be nonempty, weakly compact and convex. Let  $g : X \times Y \rightarrow \mathbb{R}$  be convex with respect to  $x \in C$  and concave and upper-semicontinuous with respect to  $y \in D$ , and weakly continuous in  $y$  when restricted to  $D$ . Then

$$d := \max_{y \in D} \inf_{x \in C} g(x, y) = \inf_{x \in C} \max_{y \in D} g(x, y) =: p. \quad (2)$$

To deduce the concrete Theorem from this theorem we simply consider

$$g(x, y) := \langle Ax, y \rangle.$$

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# Various proof techniques

In my books and papers I have reproduced a variety of proofs of the general and concrete Theorems. All have their benefits and additional features:

- The original proof via *Brouwer's fixed point theorem* [1, §8.3] and more refined subsequent algebraic-topological treatments such as the *KKM principle* [1, §8.1, Exer. 15].

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- Tucker's proof of the concrete (simplex) Theorem via *schema and linear programming* [12].

# Various proof techniques

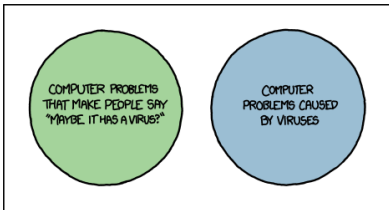
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- Tucker's proof of the concrete (simplex) Theorem via *schema and linear programming* [12].
- From a *compactness and Hahn Banach separation—or subgradient—argument* [4], [2, §4.2, Exer. 14], [3, Thm 3.6.4].
  - This approach also yields *Sion's convex-concave-like minimax theorem*, see [2, Thm 2.3.7] and [11] which contains a nice early history of the minimax theorem.

- From *Fenchel's duality theorem* applied to indicator functions and their conjugate support functions see [1, §4.3, Exer. 16], [2, Exer. 2.4.25] in Euclidean space, and in generality [1, 2, 3]. Bauschke and Combettes discuss this in Hilbert space.



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  - In J.M. Borwein and C. Hamilton, “**Symbolic Convex Analysis: Algorithms and Examples**,” *Math Programming*, **116** (2009), 17–35, we show that much of this theory can be implemented in a computer algebra system.



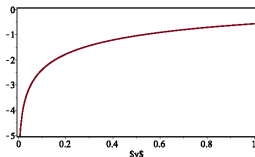
## SCAT illustrated

<http://carma.newcastle.edu.au/ConvexFunctions/links.html> $e^{e^x}$  has conjugate  $y(\log W(y) - W(y) - 1/W(y))$  (Lambert W)

```

> f11:=convert(exp(exp(x)),PWF);
                                     f11 := { e^{e^x}  all(x)
> g11:=Conj(f11,y);
                                     g11 := {
                                     ∞                y < 0
                                     -1               y = 0
                                     - y (LambertW(y)^2 - LambertW(y) ln(y) + 1) / LambertW(y)  0 < y
> sdg11:=SubDiff(g11);
                                     sdg11 := {
                                     {}                y < 0
                                     {}                y = 0
                                     {-LambertW(y) + ln(y)}  0 < y
> Plot(sdg11,y=-1..1,view=[0..1,-5..0],axes=boxed,labels=["$y$",""])
);

```



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About 35 years ago while first teaching convex analysis and conjugate duality theory, I derived the proof in Section 3, that seems still to be the most abstract and sophisticated I know.

- I derived it in order to illustrate the power of functional-analytic convex analysis as a mode of argument.
- I really do not *now* know if it was original at that time . But I did *discover* it in Giaquinto's [6, p. 50] attractive encapsulation:

*In short, discovering a truth is coming to believe it in an independent, reliable, and rational way.*

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  - For example, I have often used the *Pontryagin maximum principle* [7] of optimal control theory to discover an inequality for which I subsequently find a direct proof, say from *Jensen-like inequalities* [2].

So it seemed fitting to write the proof down for the first issue of the new journal *Minimax Theory and its Applications* dedicated to all matters minimax.

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# Needed Tools

I enumerate the prerequisite tools, sketching only the final two as they are less universally treated.

**1. Hahn-Banach separation** If  $C \subset X$  is closed and convex in a Banach space and  $x \in X \setminus C$  there exists  $\varphi \neq 0$  in  $X^*$  such that

$$\varphi(x) > \sup_{x \in C} \varphi(x)$$

as I learned from multiple sources including [7, 8].

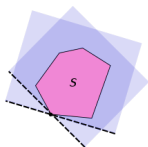
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Support and separation

We need only the Euclidean case which follows from *existence and characterisation of the best approximation* of a point to a closed convex set [1, §2.1, Exer. 8].

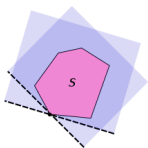
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Support and separation

We need only the Euclidean case which follows from *existence and characterisation of the best approximation* of a point to a closed convex set [1, §2.1, Exer. 8].

**2. Lagrangian duality for the abstract convex programme**, see [1, 2, 3], and [5, 8] for the standard formulation, that I learned first from Luenberger [7].

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## Theorem (Lagrange Multipliers)

Suppose that  $C \subset X$  is convex,  $f : X \rightarrow \mathbb{R}$ , is convex and  $G : X \rightarrow Y$  ordered by a closed convex cone  $S$  with nonempty norm interior is  $S$ -convex. Suppose that *Slater's condition* holds:

$$\exists \hat{x} \in X \text{ with } G(\hat{x}) \in -\text{int} S.$$

Then, the programme

$$p := \inf\{f(x) : G(x) \leq_S 0, x \in C\} \quad (3)$$

has a *Lagrange multiplier*  $\lambda \in S^+ := \{\mu : \mu(s) \geq 0, \forall s \in S\}$  so that

$$p := \inf_{x \in C} f(x) + \lambda(G(x)). \quad (4)$$

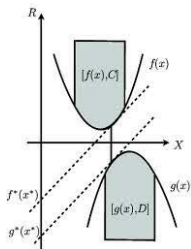
If, moreover,  $p = G(x_0)$  for a feasible  $x_0$  then *complementary slackness* obtains:  $\lambda(G(x_0)) = 0$ , while  $G(x_0) \leq_S 0$  and  $\lambda \geq_{S^+} 0$ .



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convex-concave Fenchel duality

To handle equality constraints, one needs to use cones with empty interior and to relax Slater's condition, via Fenchel duality as in [1, §4.3], [2, §4.4] or [3, Thm. 4.4.3].

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# Riesz-Markov-Kakutani representation theorem

3. (1909-1938-41) For a (locally) compact Hausdorff space  $\Omega$  the continuous function space, also Banach algebra and Banach lattice:

*$C(\Omega)$ , in the maximum norm, has dual  $M(\Omega)$  consisting of all signed regular Borel measures on  $\Omega$ .*

as I learned from Jameson, Luenberger [7] for  $\Omega := [a, b]$ , Rudin [10] and Royden [9].

- Moreover, the positive dual functionals correspond to positive measures, as follows from the lattice structure.

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# Vector integration

4. The concept of a *weak vector integral*, as I learned from Rudin [10, Ch. 3]. Given a measure space  $(Q, \mu)$  and a Hausdorff topological vector space  $Y$ , and a weakly integrable function<sup>1</sup>  $F : Q \rightarrow Y$  the integral  $y := \int_Q F(x) \mu(dx)$  is said to exist weakly if for each  $\varphi \in Y^*$  we have

$$\varphi(y) = \int_Q \varphi(F(x)) \mu(dx), \quad (5)$$

and the necessarily unique value of  $y = \int_Q F(x) \mu(dx)$  defines the *weak integral* of  $F$ .

---

<sup>1</sup>That is, for each dual functional  $\varphi$ , the function  $x \mapsto \varphi(F(x))$  is integrable with respect to  $\mu$ .

In [10, Thm. 3.27], Rudin establishes existence of the weak integral for a Borel measure on a compact Hausdorff space  $Q$ , when  $F$  is continuous and  $D := \overline{\text{conv}} F(Q)$  is compact. Moreover, when  $\mu$  is a probability measure  $\int_Q F(x) \mu(dx) \in \overline{\text{conv}} F(Q)$ .

## Proof

To show existence of  $y$  it is sufficient, since  $D$  is compact, to show that, for a probability measure  $\mu$ , (5) can be solved simultaneously in  $D$  for any finite set of linear functionals  $\{\varphi_1, \varphi_2, \dots, \varphi_n\}$ .



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$$\mathbf{m} := \left( \int_Q \varphi_1(F(x)) \mu(dx), \dots, \int_Q \varphi_n(F(x)) \mu(dx) \right)$$

and use the Euclidean space version of the Separation theorem to deduce a contradiction if  $\mathbf{m} \notin \overline{\text{conv}} T(F(Q))$ .

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and use the Euclidean space version of the Separation theorem to deduce a contradiction if  $\mathbf{m} \notin \overline{\text{conv}} T(F(Q))$ . Since  $\overline{\text{conv}} T(F(Q)) = T(D)$  we are done. ■

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# Existence and properties of a barycentre

5. We need also the concept of the *barycentre* of a non-empty weakly compact convex set  $D$  in a Banach space, with respect to a Borel probability measure  $\mu$ . As I learned from Choquet and Rudin [10, Ch. 3]), the **barycentre** (centre of mass)

$$b_D(\mu) := \int_D y \mu(dy)$$

exists and lies in  $D$ .

This is a special case of the discussion in part 4.

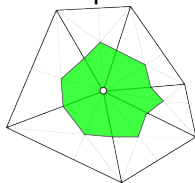
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**Barycentre** and Voronoi regions

For a **polyhedron**  $P$  with equal masses of  $1/n$  at each of the  $n$  extreme points  $\{e_i\}_{i=1}^n$  this is just

$$b_P = \frac{1}{n} \sum_{i=1}^n e_i.$$

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# Proof of the minimax theorem

We now provide the promised complicated proof.

**Proof.** We first note that always  $p \geq d$ , this is *weak duality*. We proceed to show  $d \geq p$ .

1. We observe that, on adding a dummy variable,

$$p = \inf_{x \in C} \{r : g(x, y) \leq r, \text{ for all } y \in D, r \in \mathbb{R}\}.$$

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2. Define a vector function  $G: X \times \mathbb{R} \rightarrow C(D)$  by

$$G(x, r)(y) := g(x, y) - r.$$

- This is legitimate because  $g$  is continuous in the  $y$  variable.



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- This is legitimate because  $g$  is continuous in the  $y$  variable.
- We take the cone  $S$  to be the non-negative continuous functions on  $D$  and check that  $G$  is  $S$ -convex because  $g$  is convex in  $x$  for each  $y \in D$ .

# An abstract convex programme

We now have an abstract convex programme

$$p = \inf\{r: G(x, r) \leq_S \mathbf{0}, x \in C\}, \quad (6)$$

where the objective is the linear function  $f(x, r) = r$ .

Fix  $0 < \varepsilon < 1$ . Then there is some  $\hat{x} \in C$  with  $g(\hat{x}, y) \leq p + \varepsilon$  for all  $y \in D$ . We deduce that

$$G(\hat{x}, p - 2) \leq -\mathbf{1} \in -\text{int}S$$

where  $\mathbf{1}$  is the constant function in  $C(D)$ . Thence **Slater's condition** (1953) holds.

3. The **Lagrange multiplier theorem** assures a multiplier  $\lambda \in S^+$ . By the **Riesz representation** of  $C(D)^*$ , given above, we may treat  $\lambda$  as a measure and write

$$r + \int_D (g(x, y) - r) \lambda(dy) \geq p$$

for all  $x \in C$  and all  $r \in \mathbb{R}$ . Since  $C$  is nonempty and  $r$  is arbitrary we deduce that  $\lambda(D) = \int_D \lambda(dy) = 1$  and so  $\lambda$  is a **probability measure** on  $D$ .

4. Consequently, we derive that for all  $x \in C$

$$\int_D g(x, y) \lambda(dy) \geq p.$$

5. We now consider the **barycentre**  $\hat{b} := b_D(\lambda)$  guaranteed in the prior section.

Since  $\lambda$  is a probability measure and  $g$  is continuous in  $y$  we deduce, using the integral form of *Jensen's inequality*<sup>2</sup> for the concave function  $g(x, \cdot)$ , that for each  $x \in C$

$$g(x, \int_D y \lambda(dy)) \geq \int_D g(x, y) \lambda(dy) \geq p.$$

But this says that

$$d = \sup_{y \in D} \inf_{x \in C} g(x, y) \geq \inf_{x \in C} g(x, \hat{b}) \geq p.$$

This shows the left-hand supremum is attained at the barycentre of the Lagrange multiplier. This completes the proof. ■

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<sup>2</sup>Fix  $k := y \rightarrow g(x, y)$  and observe that for any affine majorant  $a$  of  $k$  we have  $k(\hat{b}) = \inf_{a \geq k} a(\hat{b}) = \inf_{a \geq k} \int_D a(y) \lambda(dy) \geq \int_D k(y) \lambda(dy)$ , where the leftmost equality is a consequence of upper semicontinuity of  $k$ , and the second since  $\lambda$  is a probability and we have a weak integral.

# Extensions

At the expense of some more juggling with the formulation, this proof can be adapted to allow for  $g(x, y)$  only to be upper-semicontinuous in  $y$ , as is assumed in Fan's theorem.

- One looks at continuous perturbations maximizing  $G$ .

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*I will be glad if I have succeeded in impressing the idea that it is not only pleasant to read at times the works of the old mathematical authors, but this may occasionally be of use for the actual advancement of science.* (Constantin Carathéodory in 1936 speaking to the MAA)

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# Conclusions

Too often we teach the principles of functional analysis and of convex analysis with only the most obvious applications in the subject we know the most about—be it operator theory, partial differential equations, or optimization and control.



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Too often we teach the principles of functional analysis and of convex analysis with only the most obvious applications in the subject we know the most about—be it operator theory, partial differential equations, or optimization and control.

- But important mathematical results do not arrive in such prepackaged form. In my books, [1, 2, 3], my coauthors and I have tried in part to redress this imbalance. It is in this spirit that I offer this modest article.

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# The end

# with some fractal desert



# The end

# with some fractal desert



## Thank you