# **Spaces of Convex Sets**

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## **Abstract**

Throughout this presentation,  $(X,\|\cdot\|)$  will be a real normed linear space, and  $\mathcal{C}(X)$  will be the set of closed, bounded, non-empty, convex subsets of X. We examine a method for embedding  $\mathcal{C}(X)$  into a normed linear space  $\mathcal{R}(X)$ .

We also examine properties of  $\mathcal{R}(X)$ . In particular, we examine dimension, completeness, reflexivity, and separability of  $\mathcal{R}(X)$ , as well as some of its notable subspaces.

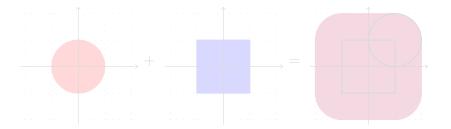
Finally, we examine the dual  $\mathcal{R}(X)^*$ , with particular reference to the Krein-Kakutani Theorem.

## Minkowski Sum

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For subsets  $A,B\subseteq X$ , the **Minkowski Sum** is defined to be

$$A + B = \{a + b : a \in A, b \in B\}.$$

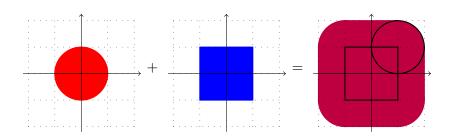


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## Closed Minkowski Sum

If  $A,B\in\mathcal{C}(X)$ , then A+B is non-empty, convex, and bounded. However, if X is not reflexive, then A+B need not be closed.

$$\oplus : \mathcal{C}(X) \times \mathcal{C}(X) : (A, B) \mapsto \overline{A + B}$$

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## Order Cancellation Law

The Closed Minkowski Sum satisfies the following order cancellation law:

#### Proposition

For any  $A,B,C\in\mathcal{C}(X)$ ,

$$A \oplus C \subseteq B \oplus C \implies A \subseteq B$$
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Using the cancellation law, we may define an equivalence relation on  $\mathcal{C}(X)\times\mathcal{C}(X)$ 

$$\sim = \{((A,B),(C,D)): A \oplus D = B \oplus C\}.$$

We define  $\mathcal{R}(X) = (\mathcal{C}(X) \times \mathcal{C}(X)) / \sim$ , and denote by  $A \ominus B$  the equivalence class of (A,B) in  $\mathcal{R}(X)$ .

We can embed  $\mathcal{C}(X)$  into  $\mathcal{R}(X)$  by identifying  $C \mapsto C \ominus \{0\}$ . We can then extend  $\oplus$  to  $\mathcal{R}(X)$  in the expected way, and  $\mathcal{R}(X)$  forms an abelian group under  $\oplus$ , with  $\ominus$  its inverse operation.

We also define a scalar multiplication operation:

$$\lambda(C \ominus D) = \begin{cases} |\lambda|C \ominus |\lambda|D : \lambda \ge 0 \\ |\lambda|D \ominus |\lambda|C : \lambda < 0 \end{cases}$$



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# Further structure of $\mathcal{R}(X)$

We also can extend the subset partial order on  $\mathcal{C}(X)$  to  $\mathcal{R}(X)$  by

$$A \ominus B \le C \ominus D \iff A \oplus D \subseteq B \oplus C.$$

This partial order makes  $\mathcal{R}(X)$  a linear lattice.  $\mathcal{R}(X)$  is also a Kakutani space:

#### Definition

A linear lattice V is a Kakutani space if

- V is Archimedean:  $\forall v, w \in V$ , if  $nv \leq w \ \forall n \in \mathbb{N}$ , then  $v \leq 0$ .
- $\exists e \in V, \forall v \in V, \exists n \in \mathbb{N}, -ne \leq v \leq ne$

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# Kakutani Spaces

Kakutani spaces induce a canonical norm:

$$||v|| = \inf\{\lambda \ge 0 : -\lambda e \le v \le \lambda e\}.$$

The canonical norm on a Kakutani space is a lattice norm, and furthermore, the associated operator norm on the dual is also a lattice norm.

In the case of  $\mathcal{R}(X)$ , this norm is derived from the Hausdorff distance:

$$||A \ominus B|| = \mathcal{H}(A, B) = \max \left\{ \sup_{a \in A} \inf_{b \in B} ||a - b||, \sup_{b \in B} \inf_{a \in A} ||a - b|| \right\}.$$

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$$[a,b] \ominus [c,d] = \begin{cases} [a-c,b-d] : a-c \le b-d \\ \ominus [c-a,d-b] : a-c > b-d \end{cases}$$

- $\mathcal{R}(\mathbb{R}) = \mathcal{C}(\mathbb{R}) \cup \ominus \mathcal{C}(\mathbb{R})$
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# Properties of $\mathcal{R}(X)$

#### Theorem

 $\mathcal{R}(X)$  is separable if and only if X is finite-dimensional. If  $\dim(X) > 1$ , then

- R(X) is incomplete, and hence not reflexive or finite-dimensional.
- The completion  $\overline{\mathcal{R}(X)}$ , or equivalently the dual  $\mathcal{R}(X)^*$ , is not reflexive.

## Induced Transformations and Subspaces

For a bounded linear transformation  $T: X \to Y$ , we may induce a bounded linear transformation from  $\mathcal{R}(X)$  to  $\mathcal{R}(Y)$ :

$$\rho_T : \mathcal{R}(X) \to \mathcal{R}(Y) : A \ominus B \mapsto \overline{T(A)} \ominus \overline{T(B)}.$$

If we consider the inclusion map T of a subspace Y into X, the image of the induced transformation  $\rho_T$  is an isometric embedding of  $\mathcal{R}(Y)$  into  $\mathcal{R}(X)$ . This gives us a subspace structure of  $\mathcal{R}(X)$  inherited from the subspace structure of X.

### Proposition

Regardless of whether Y is closed in X,  $\rho_T(\mathcal{R}(Y))$  is closed in  $\mathcal{R}(X)$ . Moreover, if Y is dense in X, then  $\rho_T$  is surjective, proving  $\mathcal{R}(X)$  and  $\mathcal{R}(Y)$  are isometrically isomorphic.



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## Induced Functionals

Equipped with our knowledge of  $\mathcal{R}(\mathbb{R})$ , we can induce functionals in  $\mathcal{R}(X)^*$  from functionals in  $X^*$ . We may consider  $\rho_f$  for  $f \in X^*$  as a bounded linear transformation of  $\mathcal{R}(X)$  into  $\mathbb{R}^2$ . We can then compose  $\rho_f$  with functionals on  $\mathbb{R}^2$  to obtain a two dimensional subspace of  $\mathcal{R}(X)^*$  spanned by the following functionals:

$$\sigma_f(A \ominus B) = \sup f(A) - \sup f(B)$$
  
 $\iota_f(A \ominus B) = \inf f(A) - \inf f(B).$ 

We say that a functional in  $\operatorname{span}\{\sigma_f, \iota_f\}$  is **induced** by f. Note in particular that  $-\iota_f = \sigma_{-f}$ .



# Structure of $\mathcal{R}(X)^*$

#### Theorem

Suppose  $\phi \in \mathcal{R}(X)^*$ . Then there exist unique scalars  $(c_f)_{f \in S_{X^*}} \in \mathbb{R}$ , all but countably many of which are 0, and  $\psi \in \mathcal{R}(X)^*$  that is lattice-orthogonal to  $\sigma_f$  for all  $f \in X^*$  such that

$$\phi = \psi + \sum_{f \in S_{X^*}} c_f \sigma_f.$$

Moreover,  $\phi$  is monotone if and only if  $c_f \geq 0$  for all  $f \in S_{X^*}$  and  $\psi$  is monotone.

## The Krein-Kakutani Theorem

## Theorem (Krein, Kakutani)

If V is a Kakutani space, then for some compact Hausdorff topological space K, V embeds densely, isometrically, and monotonically into C(K), in such a way that e maps to the constant function 1.

[Coppel, pp. 196–209] provides a self-contained proof of this form of the theorem.

In particular, the space  $K=\operatorname{ext}(V_+^*\cap S_{V^*})$ , under the weak\* topology. That is, K is the extreme points of the set of norm 1, monotone functionals in  $V^*$ . This is one good reason to study  $\mathcal{R}(X)^*$ .

# Applying The Krein-Kakutani Theorem

#### Theorem

Suppose  $K = \operatorname{ext}(\mathcal{R}(X)_+^* \cap S_{\mathcal{R}(X)^*})$ , as per the Krein-Kakutani Theorem. Then  $\{\sigma_f : f \in S_{X^*}\} \subseteq K$ , with equality holding if and only if X is finite-dimensional.

If X is finite-dimensional, there is therefore a natural bijection between K and  $S_{X^*}$ . This bijection turns out to be a homeomorphism, with  $S_{X^*}$  under the standard Euclidean topology. Therefore,

#### Corollary

If X is finite-dimensional, then  $\mathcal{R}(X)$  embeds densely, isometrically, and monotonically into  $C(S_{X^*})$ .

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## References

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